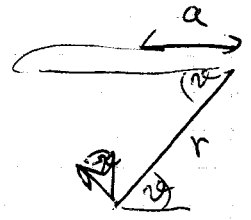
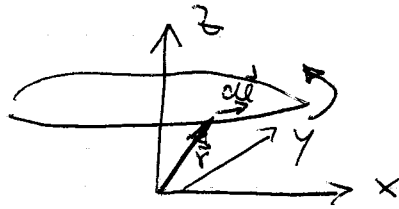


1)



$$\cos \alpha = \frac{a}{r}$$



$$\vec{B}^{(1)} = \frac{\mu_0}{4\pi} \oint \frac{I d\vec{l} \times \vec{r}}{|\vec{r}|^3}$$

$$B_z^{(1)} = \frac{\mu_0}{4\pi} \int_0^{2\pi} \frac{I \cdot a \cdot d\varphi \cdot r \cdot \cos \alpha}{r^3} = \frac{\mu_0}{2} \frac{I a^2}{r^3}$$

$$= \frac{\mu_0 I a^2}{2 \left(\sqrt{a^2 + \left(\frac{d}{2} - z\right)^2} \right)^3}$$

Analogous: $B_z^{(2)} = - \frac{\mu_0 I a^2}{2 \left(\sqrt{a^2 + \left(\frac{d}{2} + z\right)^2} \right)^3}$

$$\frac{\partial B_z^{(1)}}{\partial z} = \frac{\mu_0 I a^2}{2} \frac{-3 \cdot \left(\frac{d}{2} - z\right)}{\left(a^2 + \left(\frac{d}{2} - z\right)^2\right)^{5/2}}$$

$$\frac{\partial B_z^{(2)}}{\partial z} = - \frac{\mu_0 I a^2}{2} \frac{-3 \left(\frac{d}{2} + z\right)}{\left(a^2 + \left(\frac{d}{2} + z\right)^2\right)^{5/2}}$$

$$\left. \frac{\partial B_z}{\partial z} \right|_{z=0} = \left. \frac{\partial B_z^{(1)}}{\partial z} \right|_{z=0} + \left. \frac{\partial B_z^{(2)}}{\partial z} \right|_{z=0} = \frac{3 \mu_0 I a^2}{2} \frac{d}{\left(a^2 + \left(\frac{d}{2}\right)^2\right)^{5/2}}$$

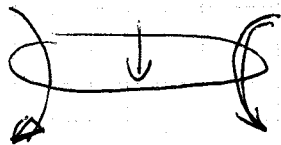
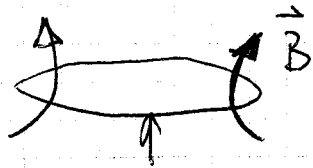
Maximum: $\frac{\partial}{\partial d} \left(\left. \frac{\partial B_z}{\partial z} \right|_0 \right) = 0$

$$0 = \frac{3 \mu_0 I a^2}{2} \left(\frac{1}{\left(a^2 + \left(\frac{d}{2}\right)^2\right)^{5/2}} - \frac{5d \cdot \frac{d}{4}}{\left(a^2 + \left(\frac{d}{2}\right)^2\right)^{7/2}} \right) = \dots \frac{a^2 + \frac{d^2}{4} - \frac{5d^2}{4}}{\dots}$$

Rezultat: $a=d$

$$\left. \frac{\partial B_z}{\partial z} \right|_0 = \frac{3 \mu_0 I a^2}{2} \frac{a}{(a^2 + (\frac{a}{2})^2)^{5/2}} = \frac{3}{2} \left(\frac{4}{5} \right)^{5/2} \frac{\mu_0 I}{a^2} = A$$

b)



Iz simetrije vidimo, da je:

B_z lih v z in
sod v x, y

$B_{x,y}$: sod v z in
lih v x, y

Hkerati mora biti zaradi simetrije $B_\varphi = 0$.

Torej pridejo v poštev samo členi:

$$\vec{B}(x, y, z) = A \cdot z \cdot \hat{e}_z + C \cdot x \cdot \hat{e}_x + C \cdot y \cdot \hat{e}_y + O(r^3)$$

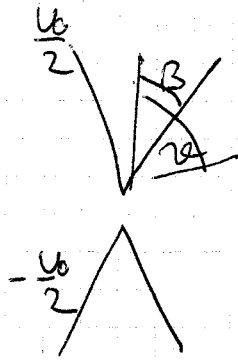
$$\text{div } \vec{B} = 0 \Rightarrow \frac{\partial B_x}{\partial x} + \frac{\partial B_y}{\partial y} + \frac{\partial B_z}{\partial z} = 0$$

$$C + C + A = 0$$

$$C = -A/2$$

$$\vec{B} = A \cdot z \cdot \hat{e}_z - \frac{1}{2} A \cdot \rho \cdot \hat{e}_\rho + O(r^3), \quad A = \frac{3}{2} \left(\frac{4}{5} \right)^{5/2} \frac{\mu_0 I}{a^2}$$

2)



Robni pogoji so odvisni samo od ϑ , zato uporabimo nastavek:

$$\phi = \phi(\vartheta)$$

$$\Delta\phi = \frac{1}{r^2} \sin^2 \vartheta \frac{\partial}{\partial \vartheta} \left(\sin \vartheta \frac{\partial \phi}{\partial \vartheta} \right) = 0$$

$$\sin \vartheta \frac{\partial \phi}{\partial \vartheta} = C$$

$$\phi = C \cdot \int \frac{d\vartheta}{\sin \vartheta} + D = C \cdot \ln \left(\tan \frac{\vartheta}{2} \right) + D$$

Zaradi simetrije: $\phi(\vartheta = \frac{\pi}{2}) = 0 \Rightarrow \underline{D=0}$

Robni pogoj: $\phi(\beta) = C \cdot \ln \left(\tan \frac{\beta}{2} \right) = \frac{U_0}{2}$

 $\sigma(r^3)$

$$C = \frac{U_0}{2 \cdot \ln \left(\tan \frac{\beta}{2} \right)}$$

$$\rightarrow \phi(\vartheta) = \frac{U_0}{2} \frac{\ln \left(\tan \left(\frac{\vartheta}{2} \right) \right)}{\ln \left(\tan \left(\frac{\beta}{2} \right) \right)}$$

$$\vec{E} = -\vec{\nabla} \phi = -\frac{1}{r} \frac{\partial \phi}{\partial \vartheta} \hat{e}_\vartheta = -\frac{1}{r} \cdot \frac{C}{\sin \vartheta} \hat{e}_\vartheta$$

$$3) \quad \phi|_R = U \cdot \cos^2 \vartheta + U_0$$

$$\underline{r > R}: \quad \phi^+ = \frac{B_0}{r} \cdot 1 + \frac{B_1}{r^2} \cdot \cos \vartheta + \frac{B_2}{r^3} \cdot \frac{3 \cos^2 \vartheta - 1}{2} + \dots$$

$$\phi^+(r=R) = U \cdot \cos^2 \vartheta + U_0$$

$B_0 = 0$, da je krogla električno neutralna.

↓

$$\underline{B_1 = 0} \quad B_2 = \frac{2}{3} U \cdot R^3 \quad B_{3,4,\dots} = 0$$

$$\phi(r, \vartheta = \frac{\pi}{2}) = \frac{2}{3} U \frac{R^3}{r^3} \left(-\frac{1}{2}\right)$$

$$E_r = -\frac{\partial \phi}{\partial r} = U \frac{R^3}{r^4}$$

$$\underline{r < R}: \quad \phi^- = A_0 + A_1 r \cdot \cos \vartheta + A_2 r^2 \frac{3 \cos^2 \vartheta - 1}{2}$$

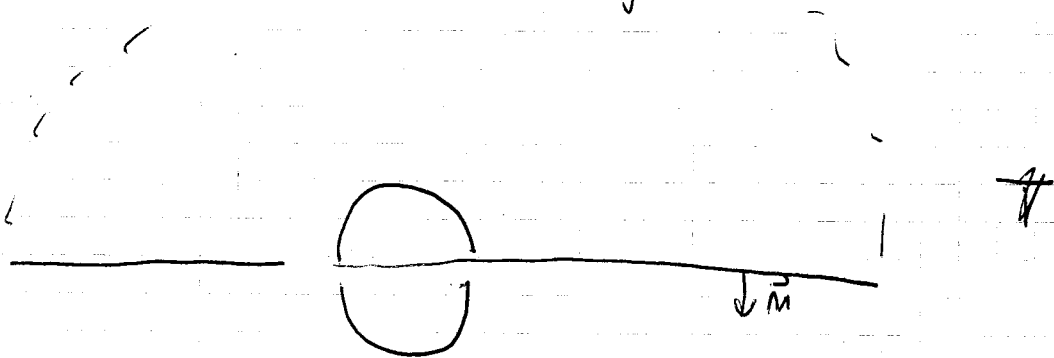
$$\phi^-(r=R) = U \cdot \cos^2 \vartheta + U_0$$

$$\hookrightarrow A_2 = \frac{2}{3R^2} \cdot U$$

$$\phi(r, \vartheta = \frac{\pi}{2}) = \frac{2}{3} U \frac{r^2}{R^2} \left(-\frac{1}{2}\right)$$

$$E_r = -\frac{\partial \phi}{\partial r} = \frac{2}{3} U \frac{r}{R^2}$$

E_z oziroma $E_{\varphi} \approx$ je pri $\vartheta = \frac{\pi}{2}$ enak 0,
zaradi simetrije.



Sila na zgornjo polovico:

$$\vec{F} = \oint \vec{T} \cdot \vec{n} \, dS, \quad F_z = \oint -T_{zz} \, dS$$

$$\text{Prizor} \quad T_{zz} = \epsilon_0 \cdot \left(E_z \cdot E_z - \frac{1}{2} E^2 \right) = -\frac{1}{2} \epsilon_0 E^2$$

$= 0 \quad \text{pri } z=0$

$$F_z = \int \frac{1}{2} \epsilon_0 E^2 \, dS = \frac{\epsilon_0}{2} \int_R^{\infty} \left(U \frac{R^3}{r^4} \right)^2 2\pi r \, dr + \frac{\epsilon_0}{2} \int_0^R \left(\frac{2U}{3} \frac{r}{R^2} \right)^2 2\pi r \, dr$$

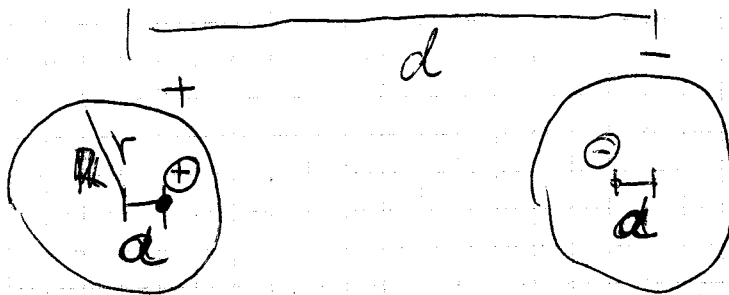
$$= \frac{\epsilon_0 U^2}{2} 2\pi \left(\frac{R^6}{6 \cdot R^6} + \frac{4}{9 \cdot 4 \cdot R^4} \right) = \underline{\underline{\frac{5}{18} \epsilon_0 \pi U^2}}$$

Positiven predznak pomeni silo navzgor,
torej je odbojna.

4) Velja $\vec{j} = \sigma \cdot \vec{E}$, $\vec{E} = -\vec{\nabla} \phi$

$$\Delta \phi = 0$$

Ker \vec{j} teče samo v ravnini x, y , je problem 2-dimenzionalen.

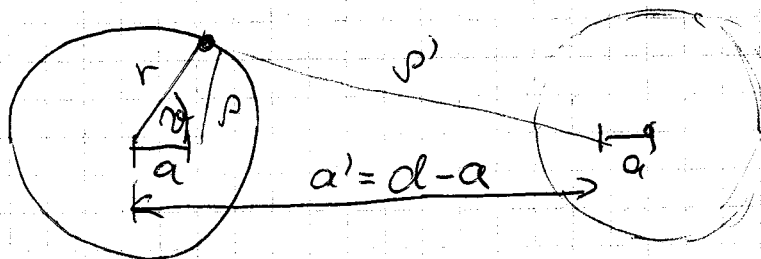


Noboj elektrode nadomestimo s premico na razdalji a od središča.

Potencial nobote premice je:

$$E_p(\rho) = \frac{(e/D)}{2\pi\epsilon_0 \rho}$$

$$\phi(\rho) = -\frac{(e/D)}{2\pi\epsilon_0} \cdot \ln \rho$$



$$\rho^2 = a^2 + r^2 - 2ra \cdot \cos \theta$$

$$\rho'^2 = a'^2 + r^2 - 2ra' \cos \theta$$

Potencial na lini električni:

$$\phi_L(\vartheta) = - \frac{(q/D)}{2\pi\epsilon_0} \cdot (\ln \rho - \ln \rho') =$$

$$= - \frac{q/D}{2\pi\epsilon_0} \cdot \ln \frac{\rho}{\rho'} =$$

$$= - \frac{q/D}{2\pi\epsilon_0} \cdot \frac{1}{2} \ln \frac{a^2 + r^2 - 2ra \cdot \cos \vartheta}{a'^2 + r^2 - 2ra' \cos \vartheta}$$

morava biti neodvisen od ϑ ,
kar je izpolnjeno, če je

$$\frac{a^2 + r^2}{2ra} = \frac{a'^2 + r^2}{2ra'}$$

$$\frac{a}{r} + \frac{r}{a} = \frac{a'}{r} + \frac{r}{a'}$$

↓

$$\frac{a'}{r} = \frac{r}{a}$$

$$\Rightarrow \boxed{a' = \frac{r^2}{a}}$$

$$a' = d - a \Rightarrow d - a = \frac{r^2}{a}$$

$$a^2 - da + r^2 = 0$$

$$a = \frac{d}{2} - \sqrt{\left(\frac{d}{2}\right)^2 - r^2}$$

$$a' = \frac{d}{2} + \sqrt{\left(\frac{d}{2}\right)^2 - r^2}$$

Izračunajmo sedbj:

$$\phi_L (v=0) = - \frac{eD}{2\pi\epsilon_0} \ln \frac{r-a}{a'-r} =$$

$$= - \frac{eD}{2\pi\epsilon_0} \cdot \ln \frac{r - \frac{r^2}{a'}}{a'-r} = \frac{eD}{2\pi\epsilon_0} \cdot \ln \frac{a'}{r}$$

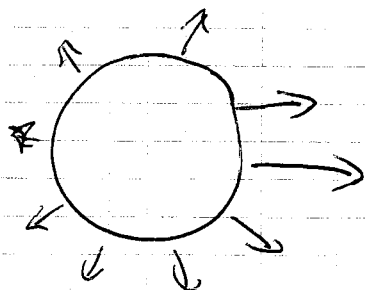
$$\frac{r(a'-r)}{a'(a'-r)}$$

$$= \frac{eD}{2\pi\epsilon_0} \cdot \ln \left(\frac{d}{2r} + \sqrt{\left(\frac{d}{2r}\right)^2 - 1} \right)$$

Zoradi simetrije: $\phi_D = -\phi_L$

$$U = \phi_L - \phi_D = 2\phi_L = \frac{eD}{\pi\epsilon_0} \cdot \ln \left(\frac{d}{2r} + \sqrt{\left(\frac{d}{2r}\right)^2 - 1} \right)$$

Tok:



$$I = \oint \vec{j} d\vec{s} = \int \sigma \cdot \vec{E} d\vec{s} =$$

$$= \frac{\sigma}{\epsilon_0} \cdot \int \vec{D} d\vec{s} = \frac{\sigma}{\epsilon_0} \cdot e$$

$$R = \frac{U}{I} = \frac{1}{\pi\sigma D} \cdot \ln \left(\frac{d}{2r} + \sqrt{\left(\frac{d}{2r}\right)^2 - 1} \right)$$